

MATH203 Calculus

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13/4/14

Vector Fields

- If to each point K in a region there is assigned exactly one vector having initial point K , then the collection of all such vectors is a **vector field**.
- A vector field in which each vector represents velocity is called a **velocity field**.
- A vector field in which each vector represents force is called a **force field**, i.e. mechanics and electricity.
- **Steady vector fields** is a vector field in which every vector is independent of time,

Vector Fields

Figure 14.1

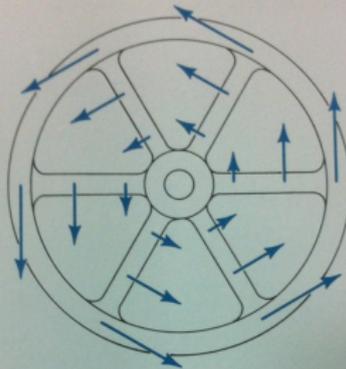


Figure 14.2



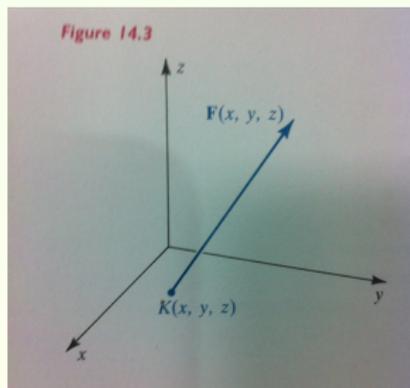
Vector Fields

Definition: Vector field in 3–dimensions

A vector field in three dimensions is a function \mathbf{F} whose domain D is a subset of \mathbb{R}^3 and whose range is a subset of V_3 . If $(x, y, z) \in D$, then

$$\mathbf{F}(x, y, z) = M(x, y, z)\mathbf{i} + N(x, y, z)\mathbf{j} + P(x, y, z)\mathbf{k},$$

where M, N and P are scalar functions.

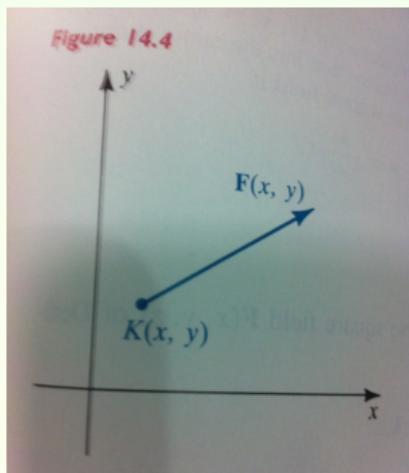


Vector Fields

Definition: Vector field in 2–dimensions

A vector field in two dimensions is a function \mathbf{F} whose domain D is a subset of \mathbb{R}^2 and whose range is a subset of V_2 . If $(x, y) \in D$, then

$$\mathbf{F}(x, y) = M(x, y)\mathbf{i} + N(x, y)\mathbf{j},$$

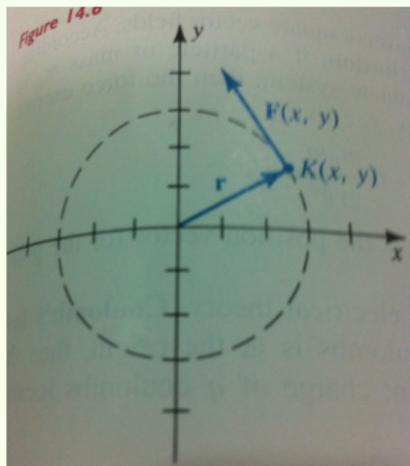


Vector Fields

Example: Describe the vector field \mathbf{F} if $\mathbf{F}(x, y) = -y\mathbf{i} + x\mathbf{j}$.

Notes:

- 1- $\mathbf{F}(x, y)$ is tangent to the circle of radius r with center at origin.
- 2- $\|\mathbf{F}(x, y)\| = \sqrt{x^2 + y^2} = \|r\|$.
- 3- This implies that $\|\mathbf{F}(x, y)\|$ increases as the point $P(x, y)$ moves away from the center.



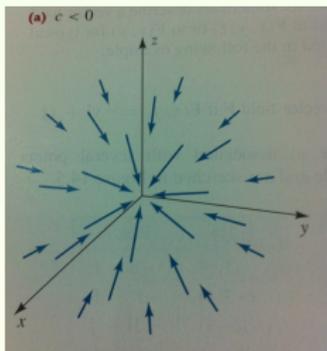
Vector Fields

Definition: Inverse Square Field

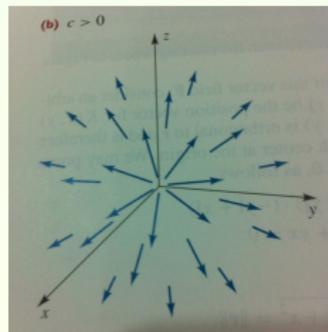
Let $\mathbf{r} = x\mathbf{i} + y\mathbf{j} + z\mathbf{k}$ be the position vector for (x, y, z) and let the vector $\mathbf{u} = \frac{1}{\|\mathbf{r}\|}\mathbf{r}$ has the same direction as \mathbf{r} . A vector field \mathbf{F} is an **inverse square field** if

$$\mathbf{F}(x, y, z) = \frac{c}{\|\mathbf{r}\|^2}\mathbf{u} = \frac{c}{\|\mathbf{r}\|^3}\mathbf{r},$$

where c is a scalar.



(a) $c < 0$



(b) $c > 0$

Vector Fields

Definition: Gradient of a function

If f is a function of three variables, the gradient of $f(x, y, z)$ is the following vector field

$$\nabla f(x, y, z) = f_x(x, y, z)\mathbf{i} + f_y(x, y, z)\mathbf{j} + f_z(x, y, z)\mathbf{k}$$

Definition: Conservative

A vector field \mathbf{F} is conservative, if

$$\mathbf{F}(x, y, z) = \nabla f(x, y, z) = f_x(x, y, z)\mathbf{i} + f_y(x, y, z)\mathbf{j} + f_z(x, y, z)\mathbf{k}$$

for some scalar function f .

Definition: Potential function

If A vector field \mathbf{F} is conservative, then f is called a **Potential function** for \mathbf{F} and $f(x, y, z)$ is potential at the point (x, y, z) .

Vector Fields

Theorem

Every inverse square vector field is conservative.

Vector differential in 3–dimensions

$$\nabla = \frac{\partial}{\partial x} \mathbf{i} + \frac{\partial}{\partial y} \mathbf{j} + \frac{\partial}{\partial z} \mathbf{k}$$

Notes:

(1) ∇ operating on a scalar function f , produces the gradient of f , i.e.

$$\text{grad}(f) = \nabla f = \frac{\partial f}{\partial x} \mathbf{i} + \frac{\partial f}{\partial y} \mathbf{j} + \frac{\partial f}{\partial z} \mathbf{k}$$

(2) ∇ operating on a vector field to define another vector field called the **curl** of \mathbf{F} , denoted by

$$\text{curl}(\mathbf{F}) = \nabla \times \mathbf{F}$$

Vector Fields

Definition: **curl**

Let $\mathbf{F}(x, y, z) = M(x, y, z)\mathbf{i} + N(x, y, z)\mathbf{j} + P(x, y, z)\mathbf{k}$, where M , N and P have partial derivatives in some region. Then,

$$\begin{aligned}\mathbf{curl}(\mathbf{F}) = \nabla \times \mathbf{F} &= \left(\frac{\partial P}{\partial y} - \frac{\partial N}{\partial z}\right)\mathbf{i} + \left(\frac{\partial M}{\partial z} - \frac{\partial P}{\partial x}\right)\mathbf{j} + \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y}\right)\mathbf{k} \\ &= \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ M & N & P \end{vmatrix}\end{aligned}$$

Definition: **divergence**

Let $\mathbf{F}(x, y, z) = M(x, y, z)\mathbf{i} + N(x, y, z)\mathbf{j} + P(x, y, z)\mathbf{k}$, where M , N and P have partial derivatives in some region. Then,

$$\mathbf{div}(\mathbf{F}) = \nabla \cdot \mathbf{F} = \frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} + \frac{\partial P}{\partial z}$$

Vector Fields

Test for conservative vector field in space

Let $\mathbf{F}(x, y, z) = M(x, y, z)\mathbf{i} + N(x, y, z)\mathbf{j} + P(x, y, z)\mathbf{k}$ is a vector field in space, where M, N and P have continuous first partial derivatives in an open region. Then, \mathbf{F} is conservative if and only if

$$\text{curl}(\mathbf{F}) = 0$$

$$\frac{\partial P}{\partial y} = \frac{\partial N}{\partial z}, \quad \frac{\partial P}{\partial x} = \frac{\partial M}{\partial z}, \quad \frac{\partial N}{\partial x} = \frac{\partial M}{\partial y}.$$

Vector Fields

Examples

(1) If $\mathbf{F}(x, y) = xy^2z^4\mathbf{i} + (2x^2y + z)\mathbf{j} + y^3z^2\mathbf{k}$, Find $\nabla \times \mathbf{F}$ and $\nabla \cdot \mathbf{F}$

(2) Find a potential function for a conservative vector field

(a) $\mathbf{F}(x, y) = 2xy\mathbf{i} + (x^2 - y)\mathbf{j}$,

(b) $\mathbf{F}(x, y, z) = -x\mathbf{i} - y\mathbf{j} - z\mathbf{k}$

(c) $\mathbf{F}(x, y, z) = 2xy\mathbf{i} + (x^2 + z^2)\mathbf{j} + 2zy\mathbf{k}$

(3) Find conservative vector field that has given potential

(a) $f(x, y, z) = x^2 - 3y^2 + 4z^2$

(b) $f(x, y, z) = \sin(x^2 + y^2 + z^2)$

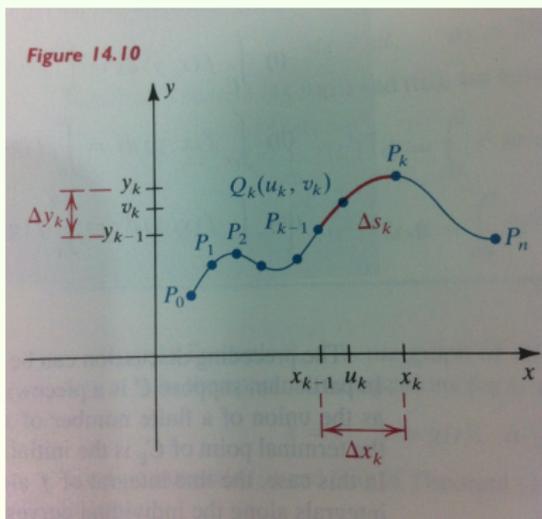
(4) Find $\nabla \times \mathbf{F}$ and $\nabla \cdot \mathbf{F}$

(a) $\mathbf{F}(x, y, z) = x^2z\mathbf{i} + y^2x\mathbf{j} + (y + 2z)\mathbf{k}$,

(b) $\mathbf{F}(x, y, z) = 3xyz^2\mathbf{i} - y^2 \sin z\mathbf{j} - xe^{2z}\mathbf{k}$

Line Integrals

We shall study the new type of integral called a **Line integral** defined by $\int_C f(x, y) ds$. Recall that a plane curve C is smooth if it has parametrisation $x = g(t)$, $y = h(t)$; $a \leq t \leq b$



Line Integrals

Let $\Delta x_k = x_k - x_{k-1}$, $\Delta y_k = y_k - y_{k-1}$ and $\Delta s_k = \text{length of } \widehat{P_{k-1}P_k}$.

Definition: Line Integrals in Two Dimensions

$$\int_C f(x, y) ds = \lim_{\|P\| \rightarrow 0} \sum_k f(x_k, y_k) \Delta s_k$$

$$\int_C f(x, y) dx = \lim_{\|P\| \rightarrow 0} \sum_k f(x_k, y_k) \Delta x_k$$

$$\int_C f(x, y) dy = \lim_{\|P\| \rightarrow 0} \sum_k f(x_k, y_k) \Delta y_k$$

where $ds = \sqrt{(dx)^2 + (dy)^2} = \sqrt{[g'(t)]^2 + [h'(t)]^2} dt$,
 $dx = g'(t)dt$ and $dy = h'(t)dt$

Line Integrals

Evaluation theorem for Line integral

If a smooth curve C is given by $x = g(t)$, $y = h(t)$; $a \leq t \leq b$ and $f(x, y)$ is continuous on region D containing C , then

$$(i) \int_C f(x, y) ds = \int_a^b f(g(t), h(t)) \sqrt{[g'(t)]^2 + [h'(t)]^2} dt$$

$$(ii) \int_C f(x, y) dx = \int_a^b f(g(t), h(t)) g'(t) dt$$

$$(iii) \int_C f(x, y) dy = \int_a^b f(g(t), h(t)) h'(t) dt$$

Line Integrals

Mass of a wire

$$m = \int_C \delta(x, y) ds$$

Examples

(1) Evaluate $\int_C xy^2 ds$ if C has parametrisation $x = \cos t, y = \sin t; 0 \leq t \leq \pi/2$.

(2) Evaluate $\int_C xy^2 dx$ and $\int_C xy^2 dy$ if C has parametrisation $y = x^2$ from $(0, 0)$ to $(2, 4)$.

(3) Evaluate $\int_C (x^2 - y + 3z) ds$ if C has parametrisation $x = t, y = 2t$ and $z = t$ from $0 \leq t \leq 1$.

(4) A thin wire is bent into the shape of a semicircle of radius a with descity $\delta = ky$. Find the mass of the wire.

Line Integrals

Examples

(1) Evaluate $\int_C xydx + x^2dy$ if

(a) C consist of line segment from $(2,1)$ to $(4,1)$ and $(4,1)$ to $(4,5)$.

(b) C is the line segment from $(2,1)$ to $(4,5)$.

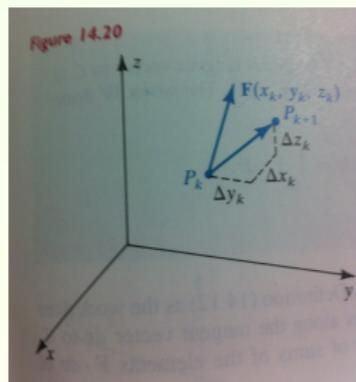
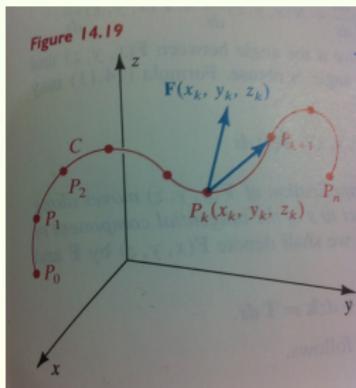
(c) C has parametrisation $x = 3t - 1, y = 3t^2 - 2t; 1 \leq t \leq 5/3$.

Line Integrals

Definition: Work done

$$\begin{aligned}
 W &= \lim_{\|P\| \rightarrow 0} \sum_k \Delta W \\
 &= \int_C M(x, y, z) dx + N(x, y, z) dy + P(x, y, z) dz
 \end{aligned}$$

This is the line integral represents the work done by the force \mathbf{F} along to the curve C .



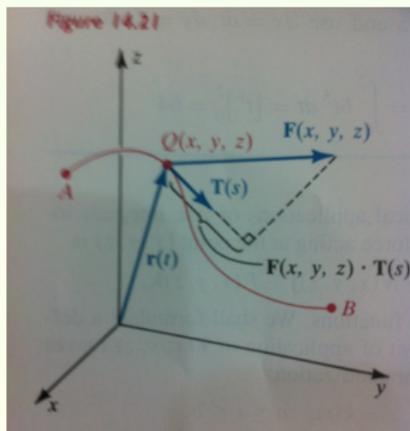
Line Integrals

Definition

Let C be a smooth space curve, Let \mathbf{T} be a unit tangential vector to C at (x, y, z) , and let \mathbf{F} be force acting at (x, y, z) . The **work done by \mathbf{F} along C** is

$$W = \int_C \mathbf{F} \cdot \mathbf{T} ds = \int_C \mathbf{F} \cdot d\mathbf{r}$$

where $\mathbf{r} = x\mathbf{i} + y\mathbf{j} + z\mathbf{k}$.



Line Integrals

Examples

(1) If an inverse force field \mathbf{F} is given by

$$\mathbf{F}(x, y, z) = \frac{k}{\|r\|^3} \mathbf{r},$$

where k is a constant, find the work done by \mathbf{F} along x -axis from $A(1, 0, 0)$ to $B(2, 0, 0)$.

(2) Let C be the part of the parabola $y = x^2$ between $(0,0)$ and $(3,9)$. If $\mathbf{F}(x, y) = -y\mathbf{i} + x\mathbf{j}$ is a force field acting at (x, y) , find the work done by \mathbf{F} along C from

- (a) $(0,0)$ to $(3,9)$
- (b) $(3,9)$ to $(0,0)$.

Line Integrals

Examples

(3) The force at a point (x, y) in a coordinate plane is given by $\mathbf{F}(x, y) = (x^2 + y^2)\mathbf{i} + xy\mathbf{j}$. Find the work done by \mathbf{F} along the graph of $y = x^3$ from $(0, 0)$ to $B(2, 8)$.

(4) The force at a point (x, y, z) in three dimensions is given by $\mathbf{F}(x, y, z) = y\mathbf{i} + z\mathbf{j} + x\mathbf{k}$. Find the work done by \mathbf{F} along the twisted cubic $x = t$, $y = t^2$, $z = t^3$ from $(0, 0, 0)$ to $B(2, 4, 8)$.

(5) Evaluate $\int_C xyz ds$ if C is the line segment from $(0, 0, 0)$ to $(1, 2, 3)$.