



مدونة المناهج السعودية

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الموقع التعليمي لجميع المراحل الدراسية

في المملكة العربية السعودية

# PHYS 101

## Ch. 8

### Momentum, Impulse and Collisions

# Chapter 8

Chapter Eight

## ***Momentum, Impulse and Collisions***

- ***Momentum and Impulse***
- ***Conservation of Momentum***
- ***Momentum Conservation and Collisions***
- ***Elastic Collisions***
- ***Center of Mass***

# Momentum and Impulse

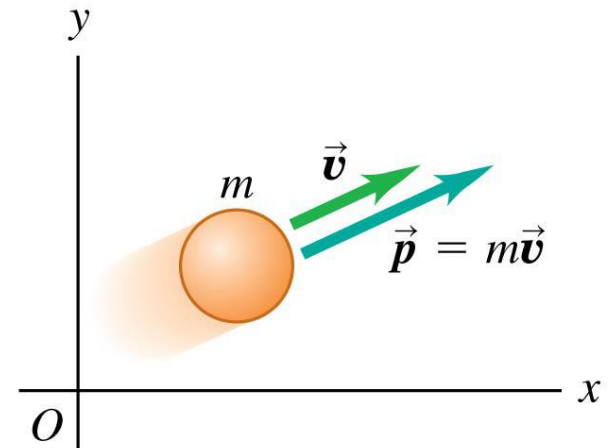
## Newton's Second Law in Terms of Momentum

### Momentum

The momentum of a particle is the product of its mass and its velocity and given by

$$\vec{p} = m\vec{v}$$

which  $m$  is the mass of the particle and  $\vec{v}$  is its velocity.



# Momentum and Impulse

Newton's second law can be written in terms of momentum

$$\vec{F}_{\text{net}} = \frac{d\vec{P}}{dt}$$

$$\vec{F}_{\text{net}} = \frac{d\vec{p}}{dt} = \frac{d}{dt} (m\vec{v}) = m \frac{d\vec{v}}{dt} = m\vec{a}.$$

## The Impulse-Momentum Theorem

The change in momentum of a particle during a time interval is equal to the impulse of the net force acting on the particle during that interval

$$\Delta\vec{p} = \vec{J}$$

(linear momentum-impulse theorem).

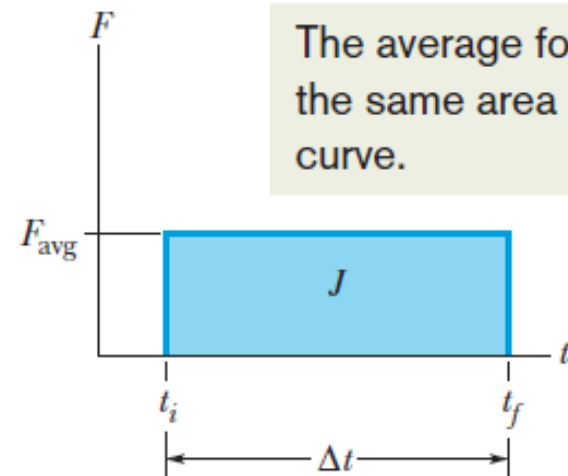
# Momentum and Impulse

## Impulse

- The impulse of a force is the product of the force and the time interval during which it acts.

- It can be given by

$$J = F_{\text{avg}} \Delta t.$$



# *Momentum and Impulse*

## *Example 1:*

A force was applied on an object of mass 50 kg which changed its speed from 13 m/s to 45 m/s. The momentum for each speed is:

## *Solution:*

**(D)**

- (A) 730 kg.m/s & 4450 kg.m/s
- (B) 850 kg.m/s & 3250 kg.m/s
- (C) 450 kg.m/s & 6550 kg.m/s
- (D) 650 kg.m/s & 2250 kg.m/s

# Momentum and Impulse

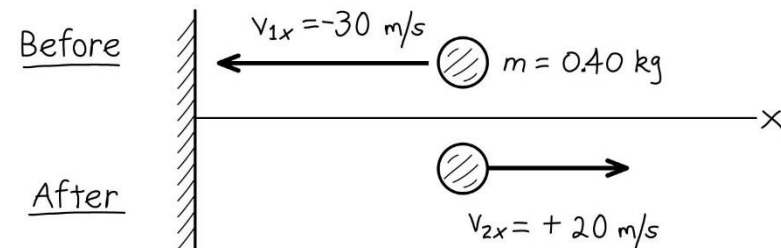
## Example 2:

A 0.40 kg ball is initially moving to the left at 30 m/s. After hitting the wall, the ball is moving to the right at 20 m/s. The impulse of the net force on the ball during its collision with the wall is:

## Solution:

(A)

- (A) 20 kg.m/s to the right
- (B) 20 kg.m/s to the left
- (C) 4.0 kg.m/s to the right
- (D) 4.0 kg.m/s to the left





# *Momentum and Impulse*

## *Example 3:*

During a collision with a wall, the velocity of a 0.200-kg ball changes from 20 m/s toward the wall to 12.0 m/s away from the wall. If the time when the ball was in contact with the wall is 60.0 ms, the magnitude of the average force applied to the ball is

## *Solution:*

**(B)**

(A) 40.0 N

(B) 107 N

(C) 16.7 N

(D) 26.7 N

# *Momentum and Impulse*

## *Example 4:*

A time-varying horizontal force  $F(t) = 4.5t^4 + 8.75t^2$  acts for 0.500 s on a 12.25-kg object. The impulse imparted to the object by this force is:

## *Solution:*

**(B)**

- (A) 8.75 N.s horizontally
- (B) 13.9 N.s horizontally
- (C) 18.2 N.s horizontally
- (D) 23.4 N.s horizontally

# Conservation of Momentum

## CONSERVATION OF MOMENTUM

If the vector sum of the external forces on a system is zero, the total momentum of the system is constant.

$$\frac{d\vec{P}}{dt} = \mathbf{0} \quad \vec{P} = \text{constant}$$

If no net external force acts on a system of particles, the total linear momentum  $\vec{P}$  of the system cannot change.

$$\vec{P}_i = \vec{P}_f$$

$$\begin{aligned} \vec{P} &= \vec{p}_1 + \vec{p}_2 + \vec{p}_3 + \dots \\ &= m_1\vec{v}_1 + m_2\vec{v}_2 + m_3\vec{v}_3 + \dots \end{aligned}$$

# *Conservation of Momentum*

## *Example 5:*

On a smooth horizontal frictionless floor, an object slides into a spring which is attached to another stationary mass. Afterward, both objects are moving at the same speed. What is conserved during this interaction?

## *Solution:*

**(C)**

- (A) momentum only
- (B) momentum and kinetic energy
- (C) momentum and mechanical energy
- (D) momentum and potential energy

# *Conservation of Momentum*

## *Example 6:*

A baseball is thrown vertically upward and feels no air resistance. As it is rising

## *Solution:*

**(B)**

(A) momentum and mechanical energy are conserved.

(B) momentum not conserved, but mechanical energy conserved.

(C) momentum and kinetic energy are conserved.

(D) kinetic energy conserved, but momentum not conserved.

# Conservation of Momentum

## Example 7:

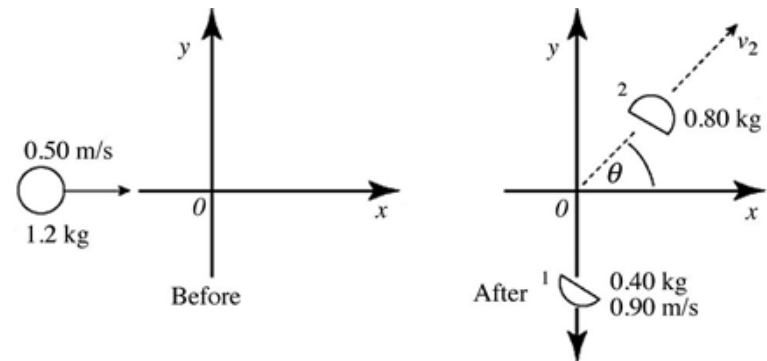
A 1.2-kg spring-activated toy bomb slides on a smooth surface along the x-axis with a speed of 0.50 m/s. At the origin 0, the bomb explodes into two fragments. Fragment 1 has a mass of 0.40 kg and a speed of 0.90 m/s along the negative y-axis. In the figure, the angle  $\theta$ , made by the velocity vector of fragment 2 and the x-axis, is closest to

## Solution:

- (A)  $31^\circ$ .
- (C)  $53^\circ$ .

- (B)  $37^\circ$ .
- (D)  $59^\circ$ .

(A)

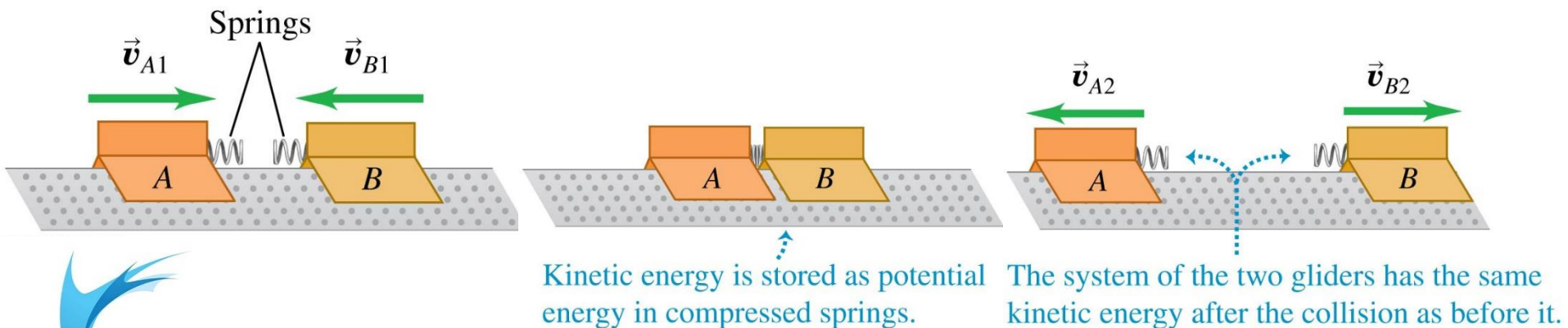


# Momentum Cons. and Collisions

## MOMENTUM CONSERVATION AND COLLISIONS

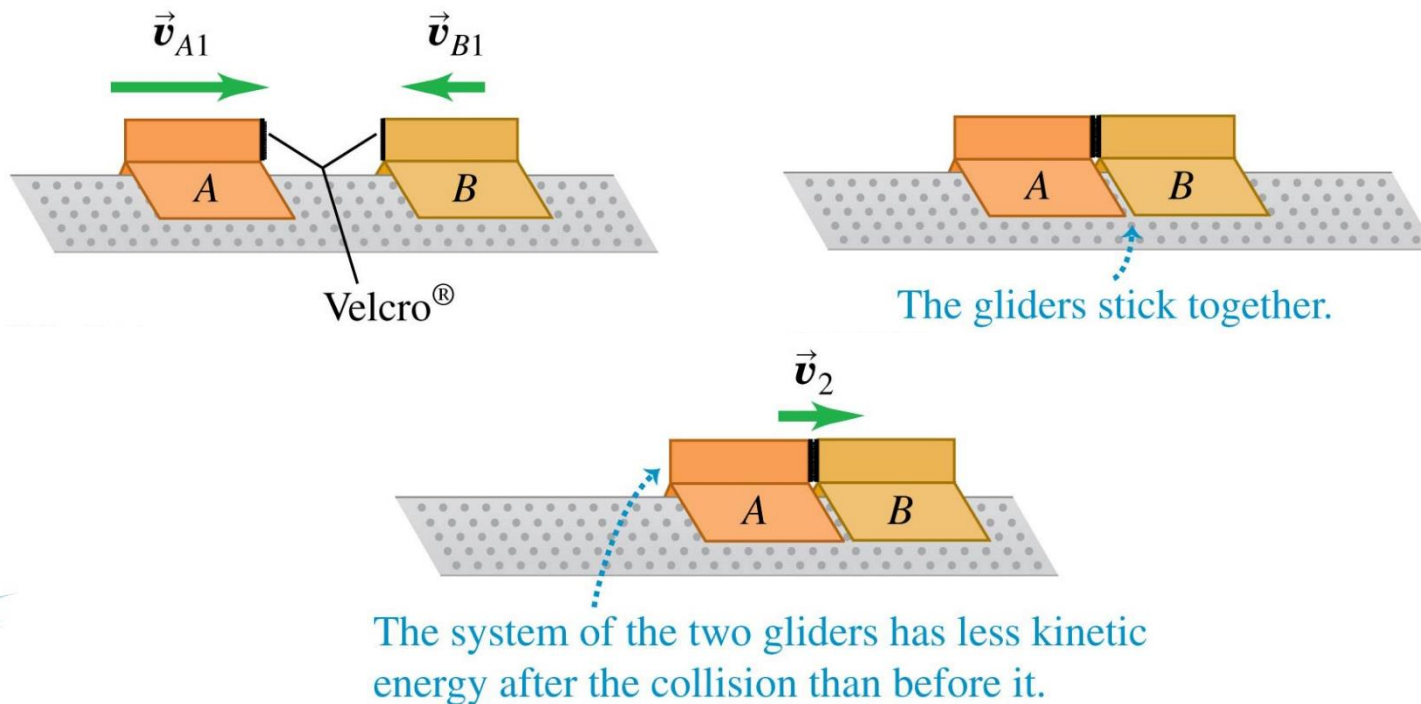
### Elastic and Inelastic Collisions

In an elastic collision, the total kinetic energy of the system is the same after the collision as before.



# Momentum Cons. and Collisions

In an inelastic collision, the total kinetic energy after the collision is less than before the collision.





# *Momentum Cons. and Collisions*

- In an inelastic collision, the total kinetic energy after the collision is less than before the collision.
- A collision in which the bodies stick together is called a completely inelastic collision.
- In any collision in which the external forces can be neglected, the total momentum is conserved.
- In elastic collisions only, the total kinetic energy before equals the total kinetic energy after.

# *Momentum Cons. and Collisions*

## Completely Inelastic Collisions

Conservation of momentum gives the relationship

$$m_A \vec{v}_{A1} + m_B \vec{v}_{B1} = (m_A + m_B) \vec{v}_2$$

for  $(v_{B1x} = 0)$   $x$ -component

$$v_{2x} = \frac{m_A}{m_A + m_B} v_{A1x}$$

# Momentum Cons. and Collisions

kinetic energies  $K_1$  and  $K_2$  before and after the collision,

$$K_1 = \frac{1}{2}m_A v_{A1x}^2$$

$$K_2 = \frac{1}{2}(m_A + m_B)v_{2x}^2 = \frac{1}{2}(m_A + m_B)\left(\frac{m_A}{m_A + m_B}\right)^2 v_{A1x}^2$$

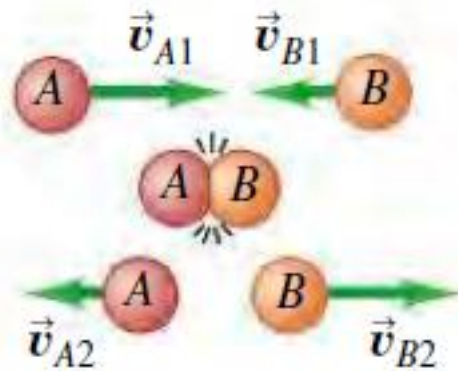
The ratio of final to initial kinetic energy is

$$\frac{K_2}{K_1} = \frac{m_A}{m_A + m_B} \quad \text{(completely inelastic collision, } B \text{ initially at rest)}$$

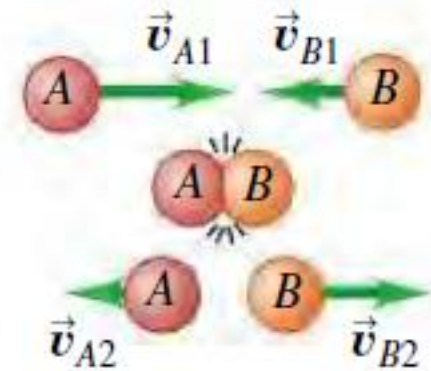
# Momentum Cons. and Collisions

## Classifying Collisions

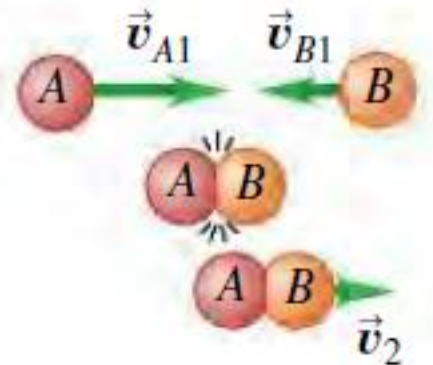
**Elastic:**  
Kinetic energy conserved.



**Inelastic:**  
Some kinetic energy lost.



**Completely inelastic:**  
Bodies have same final velocity.



# *Momentum Cons. and Collisions*

## *Example 8:*

Two objects of the same mass move along the same line in opposite directions. The first mass is moving with speed  $v$ . The objects collide, stick together, and move with speed  $0.100v$  in the direction of the velocity of the first mass before the collision. What was the speed of the second mass before the collision?

## *Solution:*

**(D)**

(A)  $1.20v$

(B)  $10.0v$

(C)  $0.900v$

(D)  $0.800v$

# Momentum Cons. and Collisions

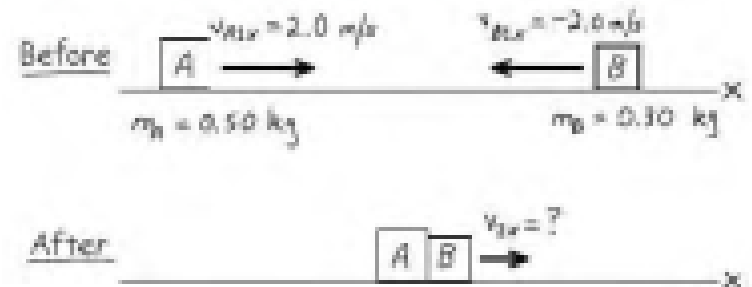
## Example 9:

Two gliders with different masses move toward each other on a frictionless air track. The gliders are equipped so that they stick together when they collide. Find the common final x-velocity?

## Solution:

- (A) 0.2 m/s
- (B) 0.5 m/s
- (C) 0.9 m/s
- (D) 1.2 m/s

(B)



# Momentum Cons. and Collisions

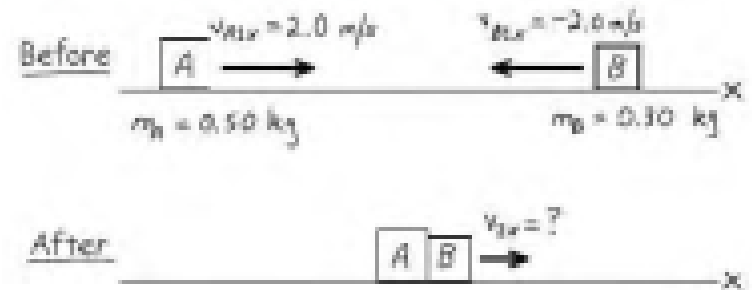
## Example 10:

Referring to Example 9, compare the initial and final kinetic energies of the system.

## Solution:

(D)

- (A)  $1/2$
- (B)  $1/4$
- (C)  $1/8$
- (D)  $1/16$



# Elastic Collisions

## ELASTIC COLLISIONS

Let's look at a *one-dimensional* elastic collision between two bodies  $A$  and  $B$ ,

From conservation of kinetic energy we have

$$\frac{1}{2}m_A v_{A1x}^2 + \frac{1}{2}m_B v_{B1x}^2 = \frac{1}{2}m_A v_{A2x}^2 + \frac{1}{2}m_B v_{B2x}^2$$

and conservation of momentum gives

$$m_A v_{A1x} + m_B v_{B1x} = m_A v_{A2x} + m_B v_{B2x}$$

If the masses  $m_A$  and  $m_B$  and the initial velocities  $v_{A1x}$  and  $v_{B1x}$  are known, we can solve these two equations to find the two final velocities  $v_{A2x}$  and  $v_{B2x}$ .



# Elastic Collisions

## Elastic Collisions, One Body Initially at Rest

$$v_{B1x} = 0$$

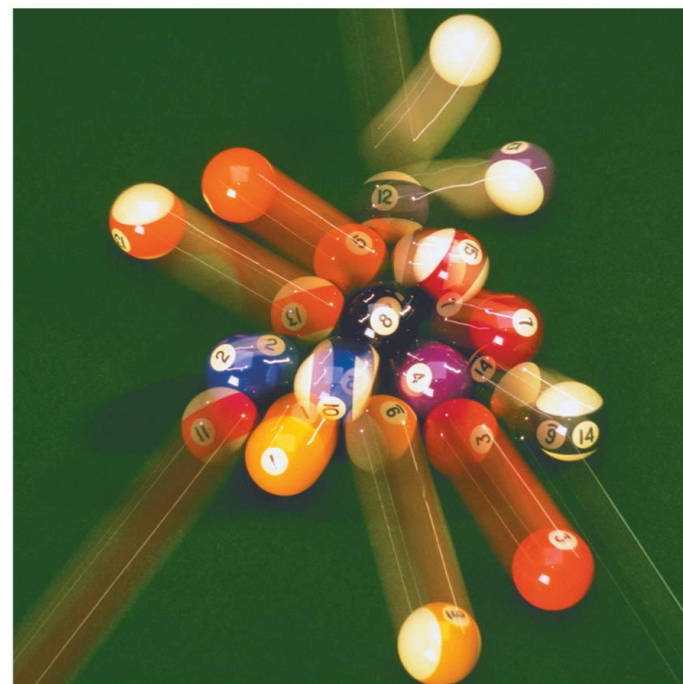
$$\frac{1}{2}m_A v_{A1x}^2 = \frac{1}{2}m_A v_{A2x}^2 + \frac{1}{2}m_B v_{B2x}^2$$

$$m_A v_{A1x} = m_A v_{A2x} + m_B v_{B2x}$$

$$v_{B2x} = v_{A1x} + v_{A2x}$$

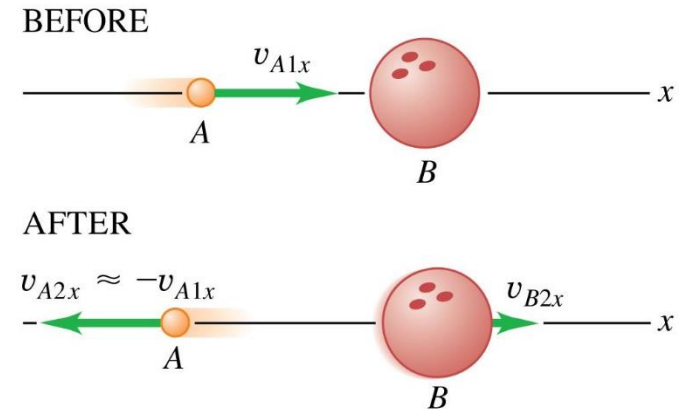
$$v_{A2x} = \frac{m_A - m_B}{m_A + m_B} v_{A1x}$$

$$v_{B2x} = \frac{2m_A}{m_A + m_B} v_{A1x}$$

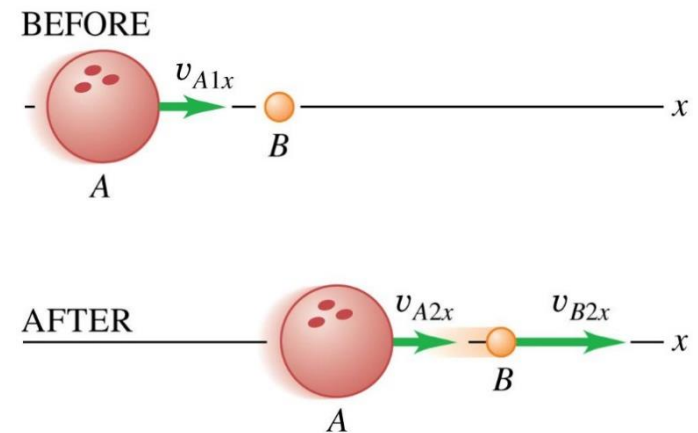


# Elastic Collisions

When B is much more massive than A, then A reverses its velocity direction, and B hardly moves.

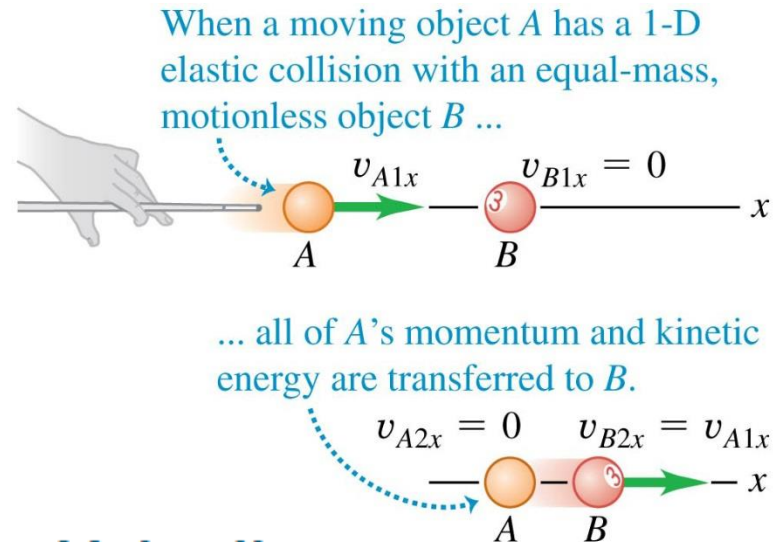


When B is much less massive than A, then A slows a little bit, while B picks up a velocity of about twice the original velocity of A.



# Elastic Collisions

When A and B have similar masses, then A stops after the collision and B moves with the original speed of A.



## Elastic Collisions and Relative Velocity

$$v_{A1x} = v_{B2x} - v_{A2x}$$

$$v_{B2x} - v_{A2x} = -(v_{B1x} - v_{A1x})$$

# Elastic Collisions

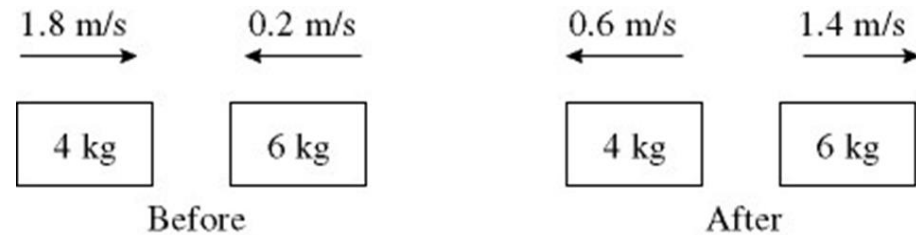
## Example 11:

In the figure, determine the character of the collision. The masses of the blocks, and the velocities before and after are given. The collision is

## Solution:

(A)

- (A) perfectly elastic.
- (B) partially inelastic.
- (C) completely inelastic.
- (D) not possible



# *Elastic Collisions*

## *Example 12:*

A 1.0 kg object travelling at 1.0 m/s collides head on with a 2.0 kg object initially at rest. Find the velocity of each object after impact if the collision is perfectly elastic.

## *Solution:*

**(C)**

(A)  $v_{1f} = -1/2 \text{ m/s}$  and  $v_{2f} = 2/3 \text{ m/s}$ .

(B)  $v_{1f} = -1/4 \text{ m/s}$  and  $v_{2f} = 2/3 \text{ m/s}$ .

(C)  $v_{1f} = -1/3 \text{ m/s}$  and  $v_{2f} = 2/3 \text{ m/s}$ .

(D)  $v_{1f} = -1/3 \text{ m/s}$  and  $v_{2f} = 2/5 \text{ m/s}$ .

# Centre of Mass

## CENTER OF MASS



The center of mass of a system of particles is the point that moves as though (1) all of the system's mass were concentrated there and (2) all external forces were applied there.

**center of mass (com)**



# Centre of Mass

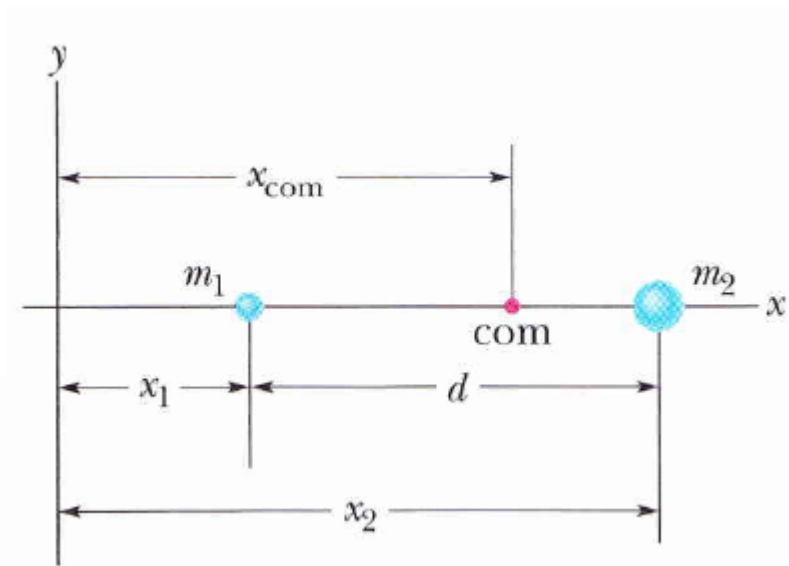
## Systems of Particles

$$x_{\text{com}} = \frac{m_1x_1 + m_2x_2}{M},$$

$$M = m_1 + m_2$$

$$x_{\text{com}} = \frac{m_1x_1 + m_2x_2 + m_3x_3 + \cdots + m_nx_n}{M}$$

$$= \frac{1}{M} \sum_{i=1}^n m_i x_i.$$

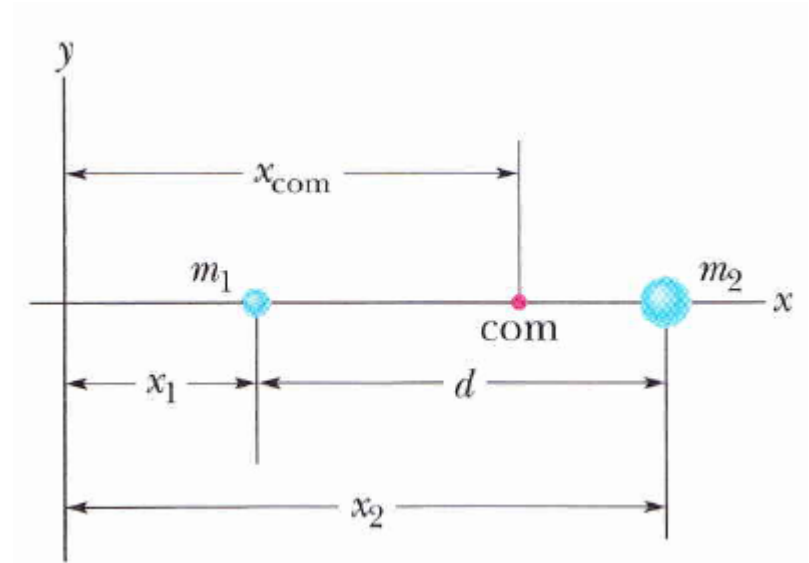


$$x_{\text{com}} = \frac{1}{M} \sum_{i=1}^n m_i x_i, \quad y_{\text{com}} = \frac{1}{M} \sum_{i=1}^n m_i y_i, \quad z_{\text{com}} = \frac{1}{M} \sum_{i=1}^n m_i z_i.$$

# Centre of Mass

$$\vec{r}_i = x_i \hat{i} + y_i \hat{j} + z_i \hat{k}.$$

$$\vec{r}_{\text{com}} = x_{\text{com}} \hat{i} + y_{\text{com}} \hat{j} + z_{\text{com}} \hat{k}.$$

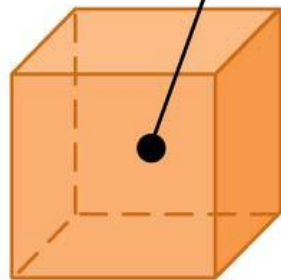


$$\vec{r}_{\text{com}} = \frac{1}{M} \sum_{i=1}^n m_i \vec{r}_i,$$

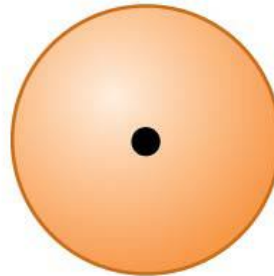


# Centre of Mass

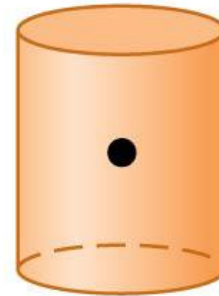
Center of mass



Cube

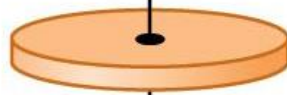


Sphere



Cylinder

Axis of symmetry



Disk



Donut

# Centre of Mass

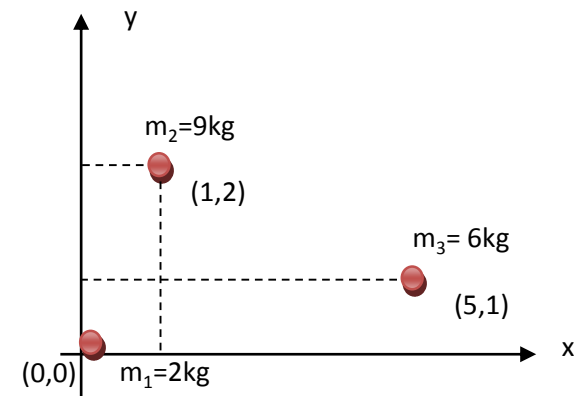
## Example 13:

The center of mass of the objects shown in the Figure is:

## Solution:

**(B)**

- (A) (3.54, 6.54) m
- (B) (2.29, 1.41) m
- (C) (4.25, 3.45) m
- (D) (5.65, 1.54) m



# Centre of Mass

## Motion of the Center of Mass

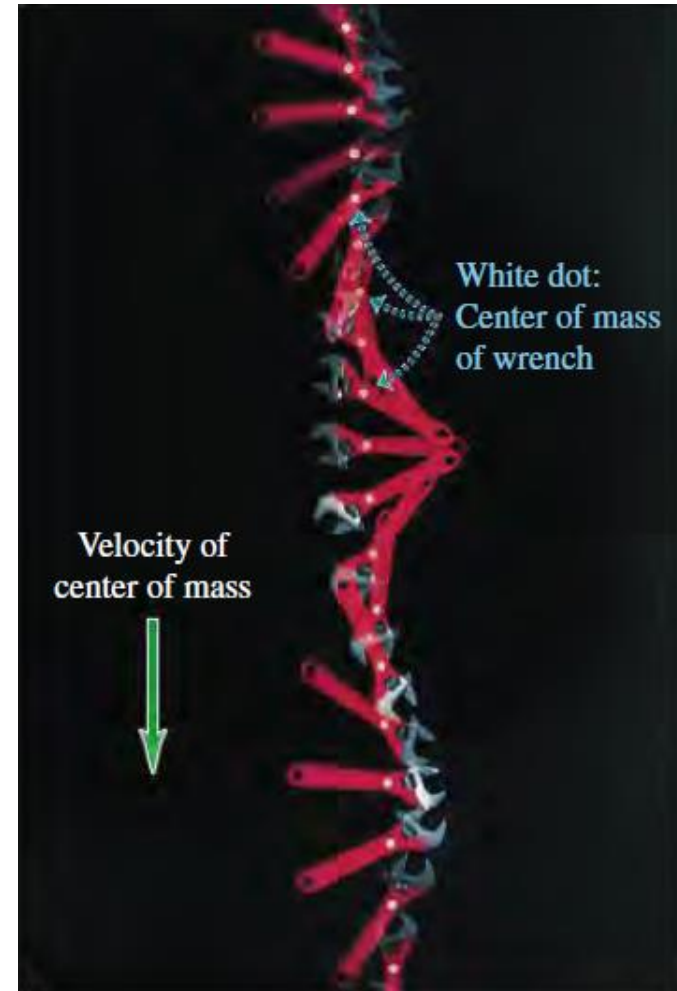
$$M\vec{r}_{\text{com}} = m_1\vec{r}_1 + m_2\vec{r}_2 + m_3\vec{r}_3 + \cdots + m_n\vec{r}_n,$$

Differentiating with respect to time gives

$$M\vec{v}_{\text{com}} = m_1\vec{v}_1 + m_2\vec{v}_2 + m_3\vec{v}_3 + \cdots + m_n\vec{v}_n.$$

Differentiating with respect to time gives

$$M\vec{a}_{\text{com}} = m_1\vec{a}_1 + m_2\vec{a}_2 + m_3\vec{a}_3 + \cdots + m_n\vec{a}_n.$$



# *Centre of Mass*

## External Forces and Center-of-Mass Motion

$$\vec{F}_{\text{net}} = M\vec{a}_{\text{com}} \quad (\text{system of particles}).$$

$$F_{\text{net},x} = Ma_{\text{com},x} \quad F_{\text{net},y} = Ma_{\text{com},y} \quad F_{\text{net},z} = Ma_{\text{com},z}.$$

# Centre of Mass

## Example 14:

Three particles as in Fig are initially at rest. experiences an external force. The directions are indicated, and the magnitudes are  $F_1=6.0$  N,  $F_2=12$  N, and  $F_3=14$  N. The acceleration of the center of mass of the system is:

### Solution:

**(B)**

(A)  $0.74 \text{ m/s}^2$

(B)  $1.16 \text{ m/s}^2$

(C)  $2.36 \text{ m/s}^2$

(D)  $4.02 \text{ m/s}^2$

